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The Chaos in g-Non Autonomous discrete systems

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Abstract---In this work, we generalized some chaotic propositions in space more general than non-autonomous discrete systems for new system we call it a g-non autonomous discrete systems.

Keywords---g-non autonomous discrete systems, sensitive dependent on initial condition, Touhey Property, strongly blending, locally eventually onto, transitive set and weakly mixing set.

Introduction

In [4] Kolyada.S and Snoha introduced space called non autonomous discrete systems, this space define by $h_n: Y \rightarrow Y$, where Y is compact topological space, $n \in \mathbb{N}$, so $h_{1,\infty}$ is the symbol to sequences begin from 1 to an infinite with $(h_1, h_2, \dots, h_n, \dots)$ such that $h_1^n(y) = h_n \circ h_{n-1} \circ \dots \circ h_1$. Lei Liu and Yuejuan Sun [5] discussed transitive set and weakly mixing set in non-autonomous discrete systems. In particular case, when $h_{1,\infty}$ be uniformly convergent to h (i.e $h_n = (h, h, h, \dots)$) then we get system called autonomous discrete system (Dynamical system) [6]. Non autonomous discrete systems are suitable for modeling some phenomena in applied Sciences, including biology [2],[7], physics [3] and economy [8], they are also useful for solving mathematical puzzles [16]. In this work, we generalized this systems such that the sequences became begin from any $n \in \mathbb{N}$ to an infinite, with $h_{n,\infty} = (h_n, h_{n+1}, \dots, h_m, \dots)$ define by $h_n^m(y) = h_m \circ h_{m-1} \circ \dots \circ h_n(y) \forall n < m \in \mathbb{N}$, and discussed some chaotic concept and chaotic properties in space more general than non-autonomous discrete systems called general-non autonomous discrete systems or g-non autonomous discrete systems.

Preliminaries

In this section, we will give generalized some definition for g-non autonomous discrete systems, so we define some chaotic concept: $h_n: Y \rightarrow Y$ is called strongly blending on g- non autonomous discrete systems if for any open sets $W, M \exists n < m \in \mathbb{N} \ni h_n^m(W) \cap h_n^m(M)$ contain an open set. also we need another definition: $h_n: Y \rightarrow Y$ is called (Locally eventually onto on g- non autonomous discrete systems if for any non-empty open subset W of $Y \exists n < m \in \mathbb{N} \ni h_n^m(W) = Y$. And we will generalize sensitive dependent on initial condition on g- non autonomous discrete systems by: $h_n: Y \rightarrow Y$ is called sensitive dependent on initial condition if $\exists \sigma > 0$ and any $y \in Y$ and W any neighborhood of y , there is $x \in Y$ and $n < m \in \mathbb{N} \ni d(h_n^m(y), h_n^m(x)) > \sigma$. In [1], Ali. B and Al-Shara'a. I introduced definition of transitive set and weakly mixing set in g-non autonomous discrete systems, and they studied some result on this definition. Now, we introduced another definition for transitive set and weakly mixing set in same spaces: A subset $\emptyset \neq B$ is called transitive set if for any $W, M \subseteq Y$ with $W \cap B \neq \emptyset$ and $M \cap B \neq \emptyset$, then $\mathcal{G}(B \cap M, W) = \{n < m \in \mathbb{N} : h_n^m(B \cap M) \cap W \neq \emptyset\}$ is an infinite. also we generalized weakly mixing set for g- non autonomous discrete systems by: Then a non-empty subset B is called Weakly mixing set with at least two element if for any open sets $W_1, W_2, \dots, W_n$ and $M_1, M_2, \dots, M_n \exists n < m \in \mathbb{N} \ni h_n^m(W_i \cap B) \cap M_i \neq \emptyset$. For any $i = 1, \dots, n$. in next section, we prove that strongly blending maps satisfy Touhey property, so we generalized Touhey property for g- non autonomous discrete systems by : h_n satisfy Touhey property if there exists two open sets W, M and $\exists y \in W$ and $n < m \in \mathbb{N} \ni h_n^m(y) \in M$.

Main Theorems

In this section, we discussed some result that need above concept on g-non autonomous discrete systems.

Theorem 3.1

Let $(Y, h_{n,\infty})$ be for g- non autonomous discrete systems system and $\{Y_i\}_{i=1,\dots,n}$ be family of transitive set where $Y_i \subseteq Y_j$, if $i \leq j$, Then $\cup_{i=1}^n \{Y_i\}$ is transitive set.

proof :

Let $B \subseteq Y$. Then by(Definition 2.4) , there exist W and M are non-empty open sets such that

$$\begin{aligned} \mathcal{G}(\cup_{i=1}^n Y_i \cap M, W) &= \{n < m \in \mathbb{N} : h_n^m(\cup_{i=1}^n Y_i \cap M) \cap W \neq \emptyset\} \\ \mathcal{G}(\cup_{i=1}^n Y_i \cap M, W) &= \{n < m \in \mathbb{N} : h_n^m((Y_1 \cap M) \cup (Y_2 \cap M) \cup \dots \cup (Y_n \cap M)) \cap W \neq \emptyset\} \end{aligned}$$

$$\mathcal{G}(\cup_{i=1}^n Y_i \cap M, W) = \{n < m \in \mathbb{N} : h_n^m(Y_1 \cap M) \cup h_n^m(Y_2 \cap M) \cup \dots \cup h_n^m(Y_n \cap M) \cap W \neq \emptyset\}$$

$$\mathcal{G}(\cup_{i=1}^n Y_i \cap M, W) = \{n < m \in \mathbb{N} : h_n^m(Y_1 \cap M) \cap W \cup h_n^m(Y_2 \cap M) \cap W \cup \dots \cup h_n^m(Y_n \cap M) \cap W \neq \emptyset\}$$

Since Y_i are transitive set, for all $i = 1, \dots, n$, then $\mathcal{G}(Y_i \cap M, W)$ is an infinite. Then $\mathcal{G}(\cup_{i=1}^n Y_i \cap M, W)$ is an infinite so $\cup_{i=1}^n \{Y_i\}$ is transitive set. ■

Proposition 3.2

Let $(Y, h_{n,\infty})$ be g - non autonomous discrete systems and B is transitive set of Y . Then $A \subseteq B$ also transitive set.

proof :

Let $\emptyset \neq W, M$ be open subset of B , then U and V are open subset of W and M respectively. So by (definition)

$$\mathcal{G}(A \cap U, V) = \{n < m \in \mathbb{N} : h_n^m(A \cap U) \cap M \neq \emptyset\} \text{ Since } A \subseteq B, \text{ then}$$

$$\mathcal{G}(A \cap U, V) \subseteq \mathcal{G}(B \cap W, M)$$

Since B is T.S, then $\mathcal{G}(B \cap W, M)$ is an infinite, so $\mathcal{G}(A \cap U, V)$ is an infinite. Then A is transitive set. ■

So in spatial case, the intersection of family of transitive set also transitive set.

Theorem 3.3

Let $(Y, h_{n,\infty})$ and $(Z, g_{n,\infty})$ be two g -NADS with $\pi : (Y, h_{n,\infty}) \rightarrow (Z, g_{n,\infty})$ be factor map and B be Weakly mixing set subset of Y . Then $\pi(B)$ is Weakly mixing subset of Z .

Proof :

In this proof, we have two cases :

Case I : if $\pi(B)$ is singleton set. then the result hold and trivial.

Case II : Let $\pi(B)$ has contain at least two element and $B \subseteq Y$ is W.M of Y . Then $\exists i, k \in \mathbb{N} \ni M_1^i, M_2^i, \dots, M_K^i$ are open subsets of $\pi(B)$ and $W_1^i, W_2^i, \dots, W_K^i$ are open subsets of Z with $W_j^i \cap \pi(B) \neq \emptyset, j = 1, 2, \dots, k$. Then $B \cap \pi^{-1}(M_j^i)$ are open subset of B and $\pi^{-1}(W_j^i)$ is

subset of Y with $\pi^{-1}(W_j^i) \cap B \neq \emptyset$, where $j = 1, \dots, k$. Since B is W.M.S of Y then $\exists n < m \in \mathbb{N}$

$$\ni h_n^m(B \cap \pi_i^{-1}(M_j^i) \cap \pi_i^{-1}(W_j^i) \neq \emptyset,$$

for each $j = 1, \dots, k$, so $g_n^m(M_j^i) \cap W_j^i \neq \emptyset$, for $i = 1, \dots, k$.

Then $\pi(B)$ is Weakly mixing subset of Z . ■

Proposition 3.4

Let $(Y, h_{n,\infty})$ be g - non autonomous discrete systems. If $cl(B)$ is transitive set, then B is transitive set.

Proof :

Assume that $cl(B)$ is transitive set, then by (Definition) there exists two non-empty open subsets W, M of Y with $W \cap B \neq \emptyset$ and $M \cap B \neq \emptyset$ such that

$\mathcal{G}(M \cap cl(B), W) = \{n < m \in \mathbb{N}, h_n^m(M \cap cl(B)) \cap W \neq \emptyset\}$ is an infinite. Since $B \subseteq cl(B)$, which impels that

$\mathcal{G}(M \cap B, W) = \{n < m \in \mathbb{N}, h_n^m(M \cap B) \cap W \neq \emptyset\}$ is an infinite so $\mathcal{G}(M \cap B, W) \neq \emptyset$. Then B is transitive set. ■

Theorem 3.5

Let $(Y, h_{n,\infty})$ be g - non autonomous discrete systems. If $h_n : Y \rightarrow Y$ are Locally eventually onto. Then $h_{n,\infty}$ is sensitive dependent on initial conditions.

Proof :

Let $\mathcal{P}, q \in Y$ such that $d(\mathcal{P}, q) > 3r$, where r positive integer number and let $\mathcal{B}_r(\mathcal{P})$ be ball with radius r and center $\mathcal{P}$ and $\mathcal{B}_r(q)$ ball with radius r and center q . Let $y \in Y$ and $S_\epsilon(y)$ open neighborhood of y for some $\epsilon > 0$. Since $h_{n,\infty}$ is locally eventually onto, there is $c_1 \in \mathbb{N}$ such that $(h_n^m)^{c_1}(\mathcal{B}_r(\mathcal{P})) = Y$, so there exists $d_1 < c_1 \in \mathbb{N}$ such that

$$(h_n^m)^{d_1}(\mathcal{B}_r(q) \cap S_\epsilon(y)) \neq \emptyset$$

And there is $d_2 < c_2$ such that

$$(h_n^m)^{d_2}(\mathcal{B}_r(q) \cap S_\epsilon(y)) \neq \emptyset$$

We take $d = \max\{d_1, d_2\}$, then there exists $x_1, x_2 \in S_\epsilon(y)$ such that

$(h_n^m)^d(x_1) \in \mathcal{B}_r(\mathcal{P})$ and $(h_n^m)^d(x_2) \in \mathcal{B}_r(q)$. Then we have

$$d((h_n^m)^d(x_1), (h_n^m)^d(x_2)) \geq \delta$$

By triangular inequality, we get

$$((h_n^m)^d(x_1), (h_n^m)^d(y)) \geq \delta \quad \text{or} \quad ((h_n^m)^d(x_2), (h_n^m)^d(y)) \geq \delta$$

Then $h_{n,\infty}$ is sensitive dependent on initial conditions. ■

Theorem 3.6

Let $(Y, h_{n,\infty})$ be with $h_n: Y \rightarrow Y$ two g -non autonomous discrete systems with continuous maps. Therefore if h_n is strongly blending and has dense periodic points, then h_n is satisfy Touhey property.

proof :

Let $\emptyset \neq W, M$ be open subsets of Y , there is $n < m \in \mathbb{N}$:

$h_n^m(W) \cap h_n^m(M)$ contain open set say U , $U \subset Y: U \subset h_n^m(W) \cap h_n^m(M)$. Now. Let $M_1 = h_n^{-m}(U) \cap M$, since U open set and h_n continuous maps,

then $h_n^{-m}(U)$ is open set, so M_1 is open set. Since The periodic points are dense then there is periodic point y of period m such that $h_n^m(y) \in U$ and

$y \in M$, so there is $p \in W: h_n^m(y) = h_n^m(p)$, therefor

$$h_n^m(p) = h_n^{m-k}(h_n^k(p)) = h_n^{m-k}(h_n^k(y)) = h_n^m(y) = y$$

So $y \in h_n^m(W) \cap M$, that mean $h_n^m(W) \cap M \neq \emptyset$, then $y \in (W)$. Then we obtained $h_{n,\infty}$ satisfy Touhey property. ■

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