



Design and Manufacture of Air Quality Measurements Based on Arduino ATmega2560 Using Dust ZH03A Laser Sensor



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Keywords

Arduino ATmega 2560;
PM1.0
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Abstract

This study aims at designing an air quality measuring instrument that is more efficient, relatively cheaper, and can be carried because. It has a smaller shape and size compared to the existing tools in the meteorology, climatology, and geophysics agency (BMKG). The main processor uses the Arduino ATmega 2560 microcontroller. This microcontroller functions as the processor for PM2.5 and PM10 concentrations which are the output of the ZH03A sensor. The design results are calibrated with a standard tool, namely BAM1020 which is owned by the BMKG air quality sector to measure air quality. The calibration results obtained that the average value issued by the reference tool which was used as a standard compared to the ZH03A sensor in the design results for PM 2.5 was 6.5 $\mu\text{m}/\text{m}^3$, and for the average value of PM1.0 was 2.8 $\mu\text{m}/\text{m}^3$ the calculated air pollution standard index (ISPU) value is 126 $\mu\text{m}/\text{m}^3$ including the medium category according to the air pollution standard index.

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1 Introduction

Bali is one of the areas that have the largest tourism destinations in Indonesia, the number of existing tourist destinations has resulted in the high arrival of foreign and domestic tourists which affect the population of this area. The high population increases the number of activities both motorized and industrial which have implications for increased air pollution and decreased air quality.

Particulate Matter (PM) is a type of hazardous pollutant and one of the parameters of air quality pollution in the Republic of Indonesia Government Regulation No. 41 of 1999 (Azhar, 2015). Particulate matter has the most dangerous impact on human health which can cause Acute Respiratory Infections (ARI). Particulate matter that is commonly found in the community is $PM_{2.5}$ and PM_{10} which are some of the parameters of air pollution. $PM_{2.5}$ is a pollutant released from vehicle emissions, which is often referred to as respirable dust because it can penetrate the lung parenchyma, causing a decrease in the vital capacity of the lungs (Falahdina, 2017). PM_{10} is a particulate size under 10 micrometers that comes from burning land and motor vehicle fumes which have a very dangerous impact on human health because its size is so small that it can reach the deepest part of the lungs and even circulate in the bloodstream (Nazaruddin, 2018).

The tools commonly used to measure air quality are the Beta Attenuation Mass Monitor 1020 (BAM-1020) and the high volume air sampler (HVAS). This tool has a very large size, making it difficult to carry anywhere (lace mobility). These tools are also limited in number and expensive so that not all places are covered by this tool in the laboratory.

We will try to design an air quality measuring instrument based on the Arduino ATmega 2560 with a laser dust sensor ZH03A with a simpler system, smaller size (Ansori, 2017; Budiyo, 2001). It has higher mobility and a much cheaper price. This design tool is expected to be able to automatically detect the level of air quality in public places, especially $PM_{2.5}$ and PM_{10} pollutants which are very dangerous to the health of the body. The tool to be designed can provide real-time air quality information and the detection results will be displayed on the LCD (Pham, 2014; Al-Haija et al., 2014).

2 Materials and Methods

The design of an air quality measuring instrument based on the Atmega 2560 microcontroller with laser dust sensor ZH03A was carried out at the Electronics and Instrumentation Laboratory of the Physics Study Program, Faculty of Mathematics and Natural Sciences, Udayana University. The overall scheme of the design tool is as Figure 1.

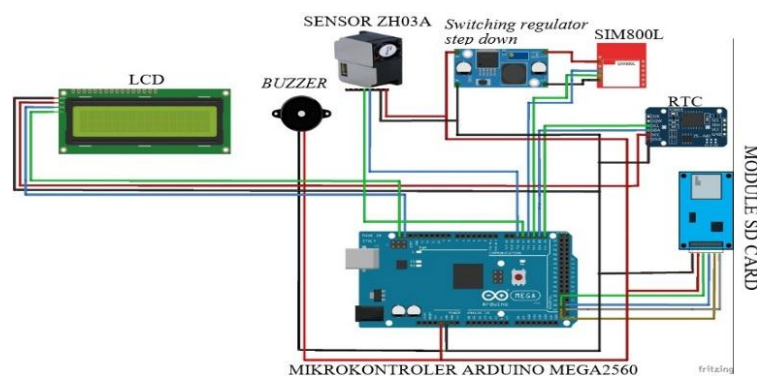


Figure 1. Schematic of the entire network of measurement systems $PM_{2.5}$ and PM_{10}

The software design uses the C language programming through the Arduino IDE application version 1.8.5. This program will always run when the microcontroller gets a voltage source (Krüger et al., 2011; Berkowicz et al., 1996). Tool design calibration is carried out by comparing it with measuring instruments available in BMKG.

3 Results and Discussions

The air quality measuring instrument has been successfully designed with a ZA03A sensor based on the ATmega 2560 microcontroller (Chandra, 2012; Fahrudin, 2014). The calibration of the design tool is carried out by comparing the ZA03A sensor reading results with the operational instrument as a reference owned by the BMKG air quality division. Testing is only carried out on parameters PM_{2.5} and PM_{1.0}.

Table 1
Results of PM_{2.5} Parameter Calibration

No.	Date	Time	Reading Results		Correction
			Reference ($\mu\text{m}/\text{m}^3$)	ZH03A. PM _{2.5} ($\mu\text{m}/\text{m}^3$)	
1	10/8/20	11:00	102	98	4
2	10/8/20	12:00	100	102	-2
3	10/8/20	13:00	98	78	20
4	10/8/20	14:00	87	98	-11
5	10/8/20	15:00	75	67	8
6	10/8/20	16:00	78	70	8
7	10/8/20	17:00	67	56	11
8	10/8/20	18:00	52	58	-6
9	10/8/20	19:00	42	58	-16
10	10/8/20	20:00	36	35	1
11	10/8/20	21:00	30	40	-10
12	10/8/20	22:00	28	52	-24
13	10/8/20	23:00	28	42	-14
14	10/8/20	24:00	26	42	-16
15	11/8/20	01:00	26	56	-30
16	11/8/20	02:00	30	34	-4
17	11/8/20	03:00	28	38	-10
18	11/8/20	04:00	42	57	-15
19	11/8/20	05:00	60	68	-8
20	11/8/20	06:00	67	78	-11
21	11/8/20	07:00	72	78	-6
22	11/8/20	08:00	89	98	-9
23	11/8/20	09:00	88	98	-10
24	11/8/20	10:00	95	101	-6
Average Difference					-6,5

In the calibration results above table, it can be seen that the average PM_{2.5} value issued by the reference tool is used as a standard compared to the ZH03A sensor at the design result is 6.5 $\mu\text{m}/\text{m}^3$.

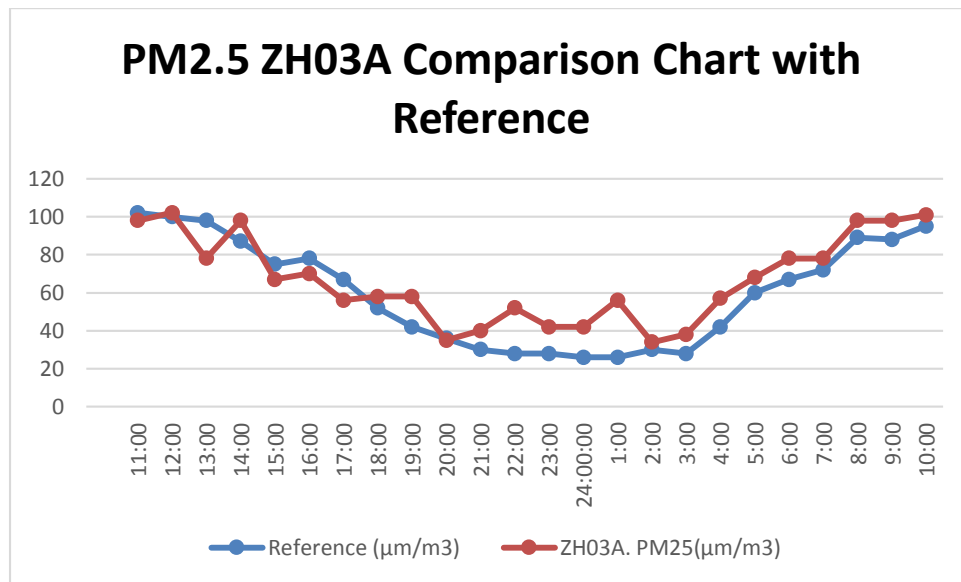


Figure 2. Comparison Graph PM2.5 ZH03A with Reference

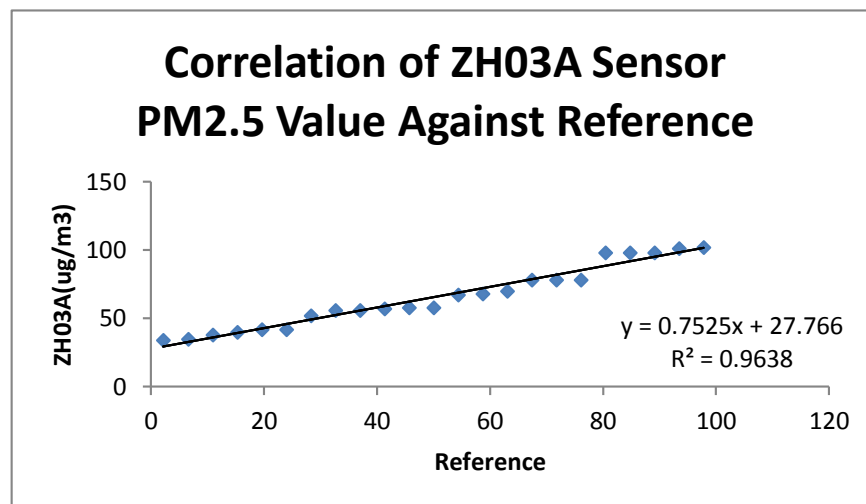


Figure 3. Correlation Graph of PM2.5 Concentration

Table 2
Calibration Results for PM1.0 Parameters

No.	Date	Time	Reading Results		Correction
			Reference (µm/m³)	ZH03A PM1.0 (µm/m³)	
1	12/8/20	11:00	108	102	6
2	12/8/20	12:00	102	98	4
3	12/8/20	13:00	89	96	-7
4	12/8/20	14:00	82	87	-5
5	12/8/20	15:00	67	75	-8
6	12/8/20	16:00	62	78	-16

7	12/8/20	17:00	56	67	-11
8	12/8/20	18:00	58	48	10
9	12/8/20	19:00	52	42	10
10	12/8/20	20:00	38	36	2
11	12/8/20	21:00	36	40	-4
12	12/8/20	22:00	30	48	-18
13	12/8/20	23:00	28	42	-14
14	12/8/20	24:00	26	42	-16
15	13/8/20	01:00	26	50	-24
16	13/8/20	02:00	30	34	-4
17	13/8/20	03:00	28	38	-10
18	13/8/20	04:00	42	34	8
19	13/8/20	05:00	60	52	8
20	13/8/20	06:00	70	50	20
21	13/8/20	07:00	80	68	12
22	13/8/20	08:00	88	70	18
23	13/8/20	09:00	80	92	-12
24	13/8/20	10:00	80	96	-16
Average Difference					-2,8

In the calibration results table above, it can be seen that the average PM1.0 value issued by the reference tool which is used as the standard compared to the ZH03A sensor in the design results is 2.8 $\mu\text{m}/\text{m}^3$.

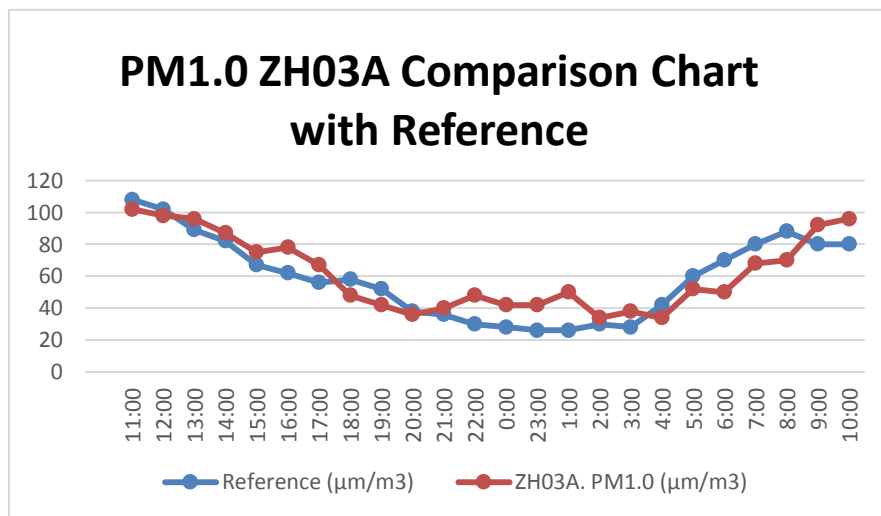


Figure 4. Comparison Graph PM1.0 ZH03A with Reference

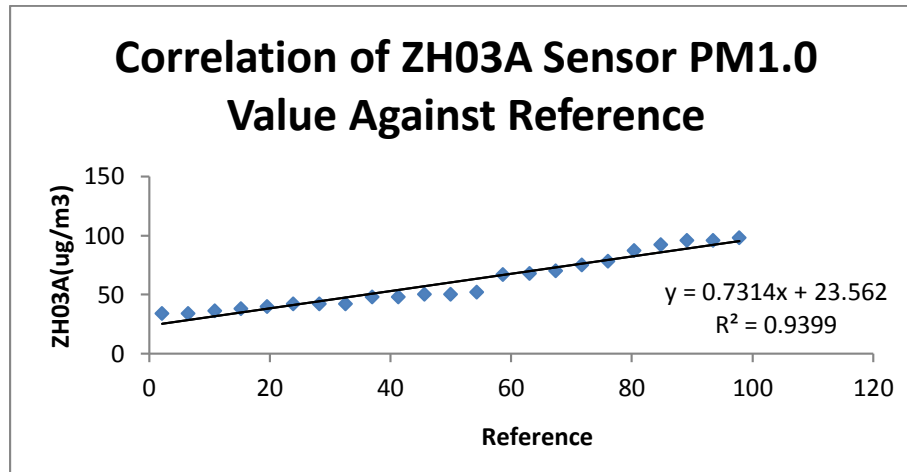


Figure 5. Graph of PM1.0 Concentration Correlation

The results calibration data of the PM2.5 and PM1.0 measurement values, the designed tool with standard tools shows that the design tool can detect the PM2.5 and PM1.0 values quite well. The value of the measurement results obtained for PM2.5 and PM1.0 read by the design tool is close to the value indicated by the calibrated operational tool, where the average correction value for PM2.5 testing is $6.5 \mu\text{m}/\text{m}^3$ and for PM1.0 test of $2.8 \mu\text{m}/\text{m}^3$, although the correction value in certain conditions is still quite far (Hatimah, et al. 2018; Dickson, 2018).

The ability of different sensors to detect particles in the air is also one of the reasons for the reading value of a slightly different tool, wherein the ZH03A sensor the smallest particle value that the sensor can read is $1 \mu\text{m}$ while in operational tools it has a better resolution of $0,1 \mu\text{m}$, so that the particulate mass that can be read is different (Rieker et al., 2007; Zatar et al., 2000). In the ZH03A sensor module, the airflow to the sensing chamber uses a small fan, while the operational equipment uses a larger fan and better suction power for air masses so that the concentration of particulates passing through the sensing chamber is greater (Pujiastuti et al., 2013; Putra, 2014). The difference in the height of the tool also affects the measurement value where the inlet height of the operational tool is higher than the design tool or the calculation of the ISPU value, using data from Table 2, namely the measurement for 24 hours starting from 11.00 to 10.00 the next day. From Table 2, it is known that the maximum value is $102 \mu\text{m}/\text{m}^3$, so to find the ISPU value can be determined from the equation as follows:

$$I = \frac{I_a - I_b}{X_a - X_b} (X_x - X_b) + I_b \quad \dots\dots\dots (1)$$

Based on data Table 2 and description of equation 2.1 it is known that $X_x = 102 \mu\text{m}/\text{m}^3$; $I_a = 100$; $I_b = 50$; $X_a = 150$; $X_b = 50$ then the ISPU value can be obtained. Based on the calculation results, the ISPU value is $126 \mu\text{m}/\text{m}^3$. Those in the range 51 to 150 are in the moderate category with decrease invisibility.

4 Conclusion

Based on the results and discussion, it can be concluded (1) it has been designed and made air quality measuring instrument which is more efficient, easy to carry, and relatively cheap price, (2) the measurement results in PM2.5 the difference in the average value between the design tool and the standard tool is $6.5 \mu\text{m}/\text{m}^3$, and in PM1.0 the difference in the average value is $2.8 \mu\text{m}/\text{m}^3$, (3) the Air Pollution Standard Index (ISPU) value from the calculation results is $126 \mu\text{m}/\text{m}^3$, included in the medium category.



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